

ΘΕΜΑ Α

A1. α

A2. β

A3. δ

A4. α

A5. α) Λάθος

β) Σωστό

γ) Σωστό

δ) Λάθος

ε) Λάθος

ΘΕΜΑ Β

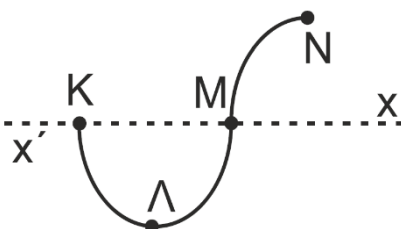
B1. Σωστή απάντηση η (iii)

$$\text{ΑΔΟ: } m \cdot u_o = 4m \cdot u_{\kappa} \Rightarrow u_{\kappa} = \frac{u_o}{4} \quad (1)$$

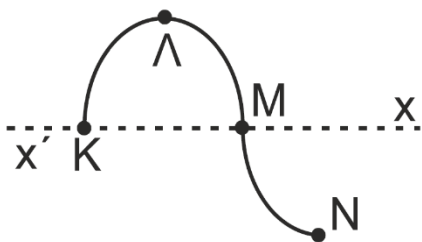
$$\frac{K_{\text{ολ.,μετά}}}{K_{1,\text{πριν}}} = \frac{\frac{1}{2} \cancel{4m} \cdot u_{\kappa}^2}{\frac{1}{2} \cancel{m} \cdot u_o^2} \stackrel{(1)}{\Rightarrow} \frac{K_{\text{ολ.,μετά}}}{K_{1,\text{πριν}}} = \frac{4 \cdot \frac{u_o^2}{16}}{u_o^2} \Rightarrow \boxed{\frac{K_{\text{ολ.,μετά}}}{K_{1,\text{πριν}}} = \frac{1}{4}}$$

B2. Σωστή απάντηση η (iii)

Για να είναι το Μ στη Θ.Ι. και $u_M < 0$ θα πρέπει να έχει στιγμιότυπο το



Οπότε μετά από $\frac{3T}{2} = T + \frac{T}{2}$ Θα είναι:



B3. Σωστή απάντηση η (ii)

$$\lambda' = \lambda + \frac{h}{m_e \cdot c} \left(1 - \cos \varphi \right) \Rightarrow \boxed{\lambda' = \lambda + \frac{h}{2 \cdot m_e \cdot c}} \quad (1)$$

$$K'_\varphi = K_e$$

$$K_\varphi = K'_\varphi + K_e \Rightarrow K_\varphi = 2K'_\varphi \Rightarrow \frac{hc}{\lambda} = 2 \frac{hc}{\lambda'} \Rightarrow \boxed{\lambda' = 2\lambda} \quad (2)$$

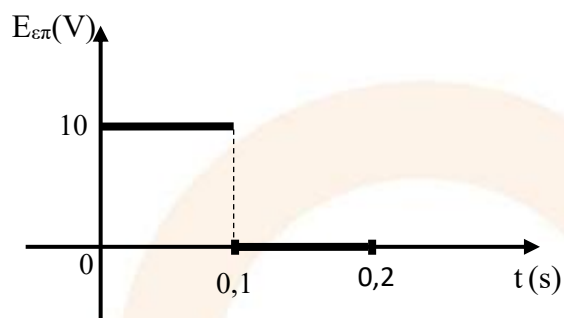
$$(1) \stackrel{(2)}{\Rightarrow} 2\lambda - \lambda = \frac{h}{2m_e \cdot c} \Rightarrow \boxed{\lambda = \frac{h}{2m_e \cdot c}} \quad (3)$$

$$K_\varphi = E_o = h \cdot f = h \cdot \frac{c}{\lambda} \stackrel{(3)}{\Rightarrow} E_o = \frac{hc}{\frac{h}{2m_e c}} \Rightarrow E_o = \frac{2m_e c^2 \cancel{h} c}{\cancel{h}} \Rightarrow \boxed{E_o = 2m_e c^2}$$

ΘΕΜΑ Γ

$$\Gamma 1. 0 \rightarrow 0,1 \text{ sec: } E_{\varepsilon\pi} = N \frac{\Delta\Phi}{\Delta t} = N \frac{\Delta B \cdot A}{\Delta t} = 100 \cdot 5 \cdot 2 \cdot 10^{-2} = 10 \text{ V}$$

$$0,1 \rightarrow 0,2 \text{ sec: } E_{\varepsilon\pi} = 0$$



Γ2. $V = N\omega BA = 100 \cdot 50\pi \cdot 0,5 \cdot 2 \cdot 10^{-2} = 50\pi \text{ V}$

$$V_{\varepsilon v} = \frac{V}{\sqrt{2}} = \frac{50\pi\sqrt{2}}{2} = 25\pi\sqrt{2} \text{ V}$$

$$I_{\varepsilon v} = \frac{V_{\varepsilon v}}{R} = \frac{25\pi\sqrt{2}}{10} = 2,5\pi\sqrt{2} \text{ A}$$

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{50\pi} = \frac{1}{25} \text{ s}$$

$$Q = I_{\varepsilon v}^2 \cdot R \cdot T = \frac{25^2 \cdot \pi^2 \cdot 2}{100} \cdot 10 \cdot \frac{1}{25} = 50 \text{ J}$$

Γ3. $\omega' = 100\pi \text{ rad/s}, \quad T' = \frac{2\pi}{\omega'} = \frac{2\pi}{100\pi} = \frac{1}{50} \text{ s}$

$$I'_{\varepsilon v} = 5\pi\sqrt{2} \text{ A}$$

$$Q' = I_{\varepsilon v}'^2 \cdot R \cdot \Delta t' = 25 \cdot \pi^2 \cdot 2 \cdot 10 \cdot \frac{1}{50} = 100 \text{ J}$$

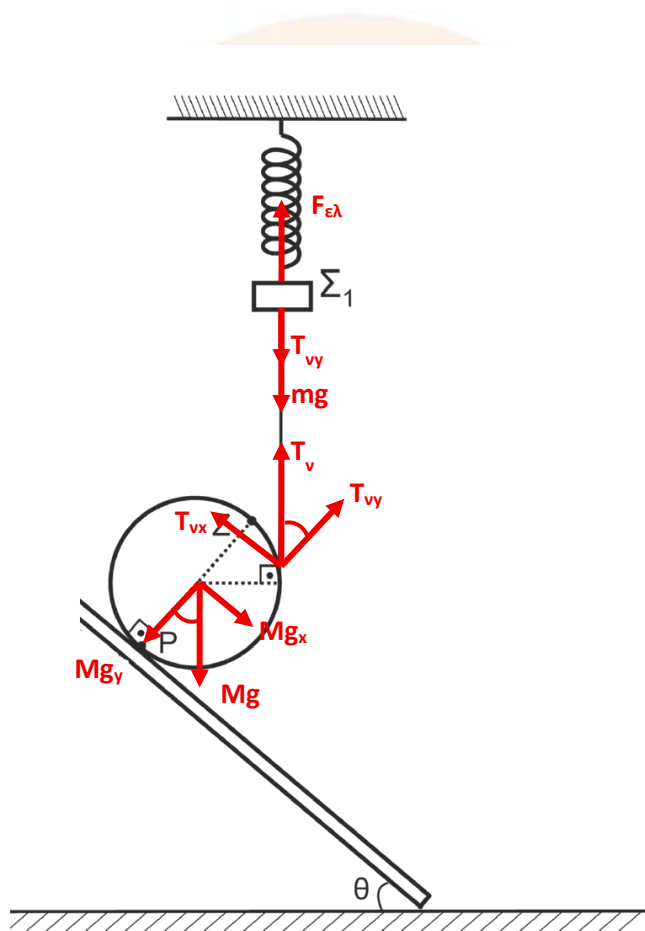
$$\Pi\% = \left[\frac{Q' - Q}{Q} \right] \cdot 100\% = \left[\frac{Q'}{Q} - 1 \right] \cdot 100\% = 100\%$$

Γ4. $I = \frac{E}{R_{\text{ολ}}} = \frac{20}{10} = 2 \text{ A}$

$$F_L = B \cdot I \cdot L = \frac{\mu_0}{4\pi} \cdot \frac{2I_1}{d} \cdot I \cdot \ell \Rightarrow F_L = 10^{-7} \cdot \frac{2 \cdot 5}{2 \cdot 10^{-2}} \cdot 2 \cdot 1 \Rightarrow F_L = 10^{-4} \text{ N}$$

ΘΕΜΑ Δ

Δ1.



$$\Sigma \tau_{(cm)} = 0 \Rightarrow T_v \cdot R = T_{\sigma\tau} \cdot R \Rightarrow T_v = T_{\sigma\tau}$$

$$\Sigma F_x = 0 \Rightarrow T_{vx} + T_{\sigma\tau} = w_x \Rightarrow T_v \cdot \eta\mu\theta + T_{\sigma\tau} = M \cdot g \cdot \sigma\upsilon\nu\theta \Rightarrow 1,6 \cdot T_v = 24 \Rightarrow T_v = 15 \text{ N}$$

$$\text{Σώμα: } \Sigma F_y = 0 \Rightarrow k \cdot \Delta l_o = m_l g + T_v \Rightarrow \Delta l_o = \frac{m_l g + T_v}{k} \Rightarrow \Delta l_o = 0,5 \text{ m}$$

Δ2. α) $\Delta\theta = 3\pi \text{ rad}$

$$\Delta x_{cm} = \Delta\theta \cdot R \Rightarrow \Delta x_{cm} = 3\pi \cdot \frac{9}{8\pi} \Rightarrow \Delta x_{cm} = \frac{27}{8} \text{ m}$$

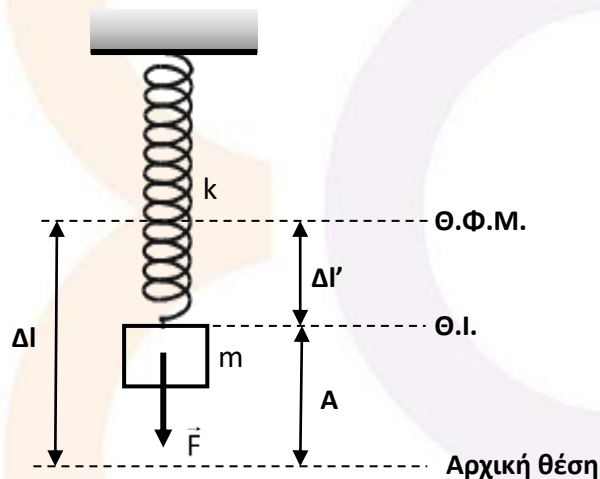
$$\beta) \Delta\theta = \frac{1}{2} \cdot \alpha_{\gamma\omega\nu} \cdot t^2 \Rightarrow 3\pi = \frac{1}{2} \cdot \alpha_{\gamma\omega\nu} \cdot 1,5^2 \Rightarrow \alpha_{\gamma\omega\nu} = \frac{8\pi}{3} \text{ rad/s}^2$$

$$\alpha_{\text{cm}} = \alpha_{\gamma\omega\nu} \cdot R \Rightarrow \alpha_{\text{cm}} = 3 \text{ m/s}^2$$

$$u_{\text{cm}} = \alpha_{\text{cm}} \cdot t \Rightarrow u_{\text{cm}} = 4,5 \text{ m/s}$$

$$u = \sqrt{u_{\text{cm}}^2 + u_{\gamma\phi}^2} = \sqrt{2u_{\text{cm}}^2} \Rightarrow u = 4,5\sqrt{2} \text{ m/s}$$

Δ3.



$$\text{Για το ελατήριο } \omega = \sqrt{\frac{k}{m_1}} \Rightarrow \omega = \sqrt{40} = 2\pi \text{ r/s}$$

$$\text{και } T = \frac{2\pi}{\omega} \Rightarrow T = 1 \text{ sec.}$$

$$N = \frac{\Delta t}{T} = \frac{1,5}{1} \Rightarrow N = 1,5 \text{ ταλαντ.}$$

$$\text{Αρχικά } \Delta l = 0,5 \text{ m}$$

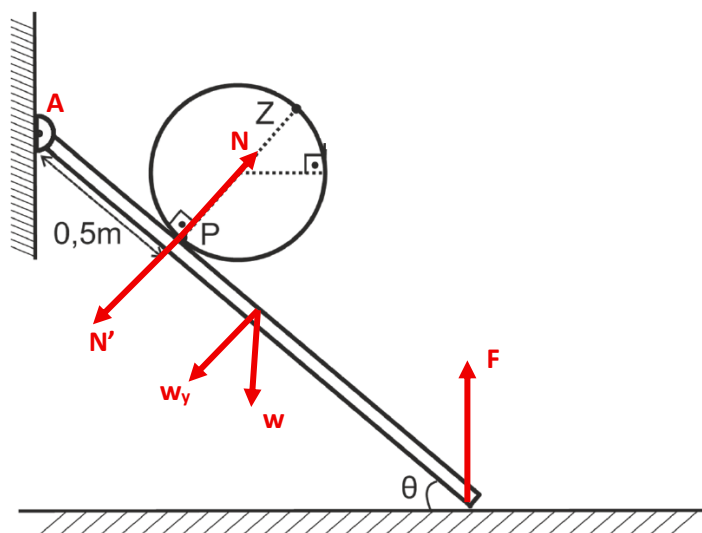
$$\text{Τελικά } \Sigma F = 0 \Rightarrow \Delta l' = \frac{m \cdot g}{k} \Rightarrow \Delta l' = 0,25 \text{ m}$$

$$\text{Άρα } A = \Delta l - \Delta l' \Rightarrow A = 0,25 \text{ m}$$

Το σώμα ξεκινάει από την κάτω ακραία θέση και μετά απο μιάμιση ταλάντωση φτάνει στην άνω ακραία θέση που συμπίπτει με την θέση φυσικού μήκους του ελατηρίου άρα $\Delta l = 0$.

$$\text{Άρα } WF_{\text{ελ.}} = U_{\text{αρχ. (ελ.)}} - U_{\text{τελ. (ελ.)}} \Rightarrow WF_{\text{ελ.}} = U_{\text{αρχ. (ελ.)}} - 0 = \frac{1}{2} k \Delta l'^2 = 7,5 \text{ J}$$

Δ4.



$$\Sigma \tau_{(A)} = 0 \Rightarrow F \cdot L \cdot \sigma\upsilon\nu\theta - w_y \cdot \frac{L}{2} - N'(0,5 + x) = 0$$

$$F \cdot L \cdot \sigma\upsilon\nu\theta = m_{\delta} \cdot g \cdot \sigma\upsilon\nu\theta \cdot \frac{L}{2} + N'(0,5 + x)$$

$$F \cdot 4 \cdot 0,8 = 16 + 32 \cdot (0,5 + x) \Rightarrow F \cdot 3,2 = 16 + 32x + 16$$

$$\boxed{F = 10 + 10x} \text{ (S.I.) } 0 \leq x \leq 3\text{m}$$



Για $x = 0 \rightarrow F = 10\text{N}$

Για $x = 3\text{m} \rightarrow F = 40\text{N}$